

## réducteur rotet roulant

$$\underline{Q1.} \quad \frac{\omega_c/ps}{\omega_p/ps} = -\frac{Z_p}{Z_s} \times \frac{Z_{s'}}{Z_c}$$

$$\frac{\omega_c/o - \omega_{ps/o}}{\omega_p/o - \omega_{ps/o}} = \boxed{-\frac{Z_p}{Z_s} \times \frac{Z_{s'}}{Z_c} = \lambda}$$

$$\Leftrightarrow \omega_c/o - \omega_{ps/o} = \lambda(\omega_p/o - \omega_{ps/o})$$

$$\omega_c/o - \lambda \omega_p/o + \omega_{ps/o}(\lambda - 1) = 0$$

$$\underline{Q2.} \quad \text{si } \omega_c/o = 0 \text{ alors } \boxed{\frac{\omega_{ps/o}}{\omega_p/o} = \frac{\lambda}{\lambda - 1}}$$

$$\underline{Q3.} \quad r_1 = \frac{\omega_{ps/o}}{\omega_p/o} = \frac{\lambda}{\lambda - 1} \quad \text{avec } \lambda = -\frac{Z_p}{Z_s} \times \frac{Z_{s'}}{Z_c}$$

$$\lambda = -\frac{9}{18} \times \frac{14}{42} = -0,1\bar{6}$$

$$r_1 = \frac{\omega_{ps/o}}{\omega_p/o} = 0,1429$$

$$r_g = r_1^3 \quad \boxed{r_g = 2,91 \cdot 10^{-3}}$$

$$\underline{Q4.} \quad V_{rotet/o} = \frac{\phi_{rouleau}}{2} \times N_{ps/o} \times \frac{2\pi}{60} = \frac{\phi_{rouleau}}{2} \times r_g \times N_{moteur} \times \frac{2\pi}{60}$$

$$\boxed{V_{rotet/o} = 29,3 \text{ mm/s}} \approx 3 \text{ cm/s}$$