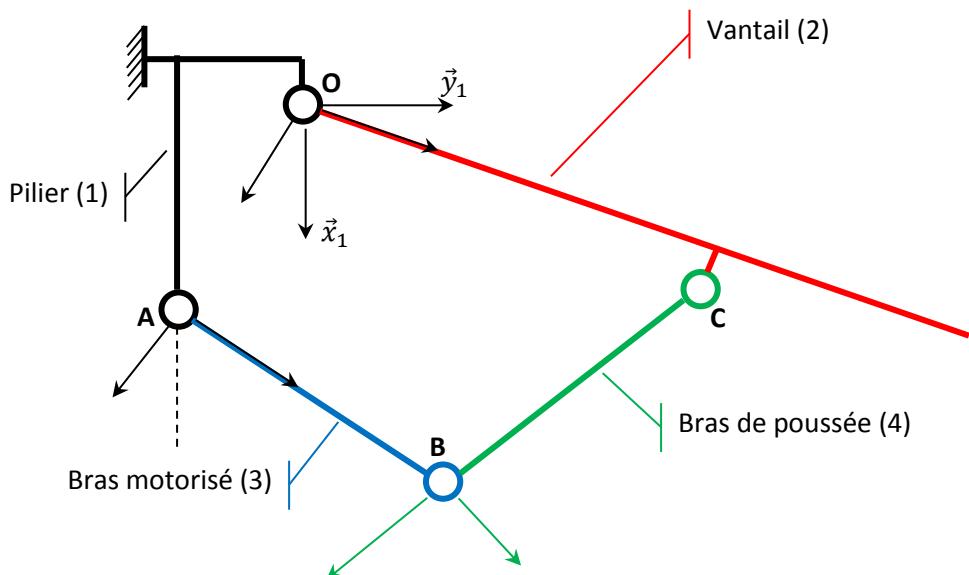
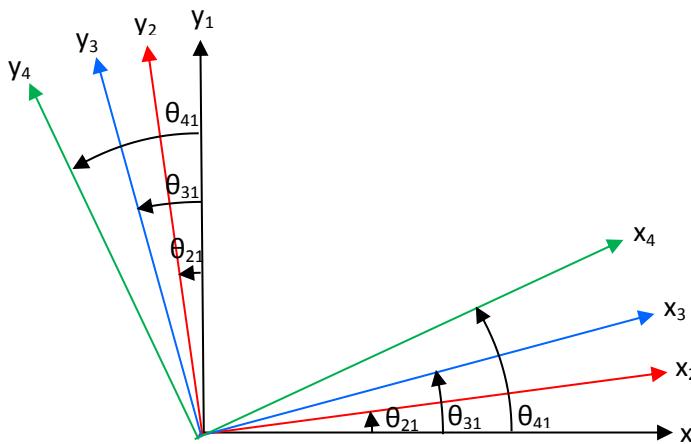


# CORRIGE Document A3\_DR1\_Portail

Schéma cinématique minimal plan ( $\vec{x}_1, \vec{y}_1$ )



## Figures de changement de base



$$\begin{aligned}\overrightarrow{OA} &= b \cdot \vec{x}_1 - a \cdot \vec{y}_1 \\ \overrightarrow{CB} &= l \cdot \vec{x}_4 \\ \overrightarrow{OC} &= c \cdot \vec{x}_2 - d \cdot \vec{y}_2 \\ \overrightarrow{AB} &= l \cdot \vec{y}_3\end{aligned}$$

$$\begin{aligned}a &= 100 \text{ mm} \\ b &= 260 \text{ mm} \\ c &= 324 \text{ mm} \\ l &= 280 \text{ mm} \\ d &= 20 \text{ mm}\end{aligned}$$

## Fermetures géométriques

$$\begin{aligned}\overrightarrow{OA} + \overrightarrow{AB} + \overrightarrow{BC} + \overrightarrow{CO} &= \vec{0} \\ b \cdot \vec{x}_1 - a \cdot \vec{y}_1 + l \cdot \vec{y}_3 - l \cdot \vec{x}_4 - c \cdot \vec{x}_2 + d \cdot \vec{y}_2 &= \vec{0}\end{aligned}$$

## Projections

$$\begin{array}{ll}\text{projection sur } \vec{x}_1 & b - 0 - l \cdot \sin \theta_{31} - l \cdot \cos \theta_{41} - c \cdot \cos \theta_{21} - d \cdot \sin \theta_{21} = 0 \\ \text{projection sur } \vec{y}_1 & 0 - a + l \cdot \cos \theta_{31} - l \cdot \sin \theta_{41} - c \cdot \sin \theta_{21} + d \cdot \cos \theta_{21} = 0\end{array}$$

## Résolution : loi d'entrée-sortie

ça pique....

en éliminant  $\theta_{41}$  par  $\cos^2 \theta_{41} + \sin^2 \theta_{41} = 1$

$$\frac{b - l \cdot \sin \theta_{31} - c \cdot \cos \theta_{21} - d \cdot \sin \theta_{21}}{l} = \cos \theta_{41}$$

$$\frac{-a + l \cdot \cos \theta_{31} - c \cdot \sin \theta_{21} + d \cdot \cos \theta_{21}}{l} = \sin \theta_{41}$$

$$(-a + l \cdot \cos \theta_{31} - c \cdot \sin \theta_{21} + d \cdot \cos \theta_{21})^2 + (b - l \cdot \sin \theta_{31} - c \cdot \cos \theta_{21} - d \cdot \sin \theta_{21})^2 = l^2$$

et en développant on obtient la relation  $A(\theta_{31}) \cdot \cos \theta_{21} + B(\theta_{31}) \cdot \sin \theta_{21} + C(\theta_{31}) = 0$

avec :

$$A(\theta_{31}) = 2 \cdot (-b \cdot c - a \cdot d - c \cdot l \cdot \cos \theta_{31} + d \cdot l \cdot \sin \theta_{31})$$

$$B(\theta_{31}) = 2 \cdot (-b \cdot d + a \cdot c - c \cdot l \cdot \sin \theta_{31} - d \cdot l \cdot \cos \theta_{31})$$

$$C(\theta_{31}) = a^2 + b^2 + c^2 + d^2 + 2 \cdot l \cdot (-a \cdot \sin \theta_{31} + b \cdot \cos \theta_{31})$$

$$A \cdot \cos \theta_{21} + B \cdot \sin \theta_{21} = -C$$

$$(A \cdot \cos \theta_{21} + B \cdot \sin \theta_{21}) = \sqrt{A^2 + B^2} \cdot \left( \frac{A}{\sqrt{A^2 + B^2}} \cdot \cos \theta_{21} + \frac{B}{\sqrt{A^2 + B^2}} \cdot \sin \theta_{21} \right)$$

$$(A \cdot \cos \theta_{21} + B \cdot \sin \theta_{21}) = \sqrt{A^2 + B^2} \cdot (\cos \alpha \cdot \cos \theta_{21} + \sin \alpha \cdot \sin \theta_{21}) = \sqrt{A^2 + B^2} \cdot \cos(\theta_{21} - \alpha)$$

$$\text{avec } \alpha = \tan^{-1} \left( \frac{B}{A} \right)$$

$$\sqrt{A^2 + B^2} \cdot \cos \left( \theta_{21} - \tan^{-1} \left( \frac{B}{A} \right) \right) = -C$$

$$\theta_{21} = \cos^{-1} \left( -\frac{C}{\sqrt{A^2 + B^2}} \right) + \tan^{-1} \left( \frac{B}{A} \right)$$

avec :

$$A(\theta_{31}) = 2 \cdot (-b \cdot c - a \cdot d - c \cdot l \cdot \cos \theta_{31} + d \cdot l \cdot \sin \theta_{31})$$

$$B(\theta_{31}) = 2 \cdot (-b \cdot d + a \cdot c - c \cdot l \cdot \sin \theta_{31} - d \cdot l \cdot \cos \theta_{31})$$

$$C(\theta_{31}) = a^2 + b^2 + c^2 + d^2 + 2 \cdot l \cdot (-a \cdot \sin \theta_{31} + b \cdot \cos \theta_{31})$$